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Before Applying DC Power Supply

Verify that DC power supply is good condition and safe to use. It is imperative to use ONE DC power supply as a source power for this product and the input voltage is no more than 38 V, or it can impair this product. Make all connections to the unit before applying power.

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Do Not Alter the Instrument

Do not put any unauthorized parts or modify the instrument without Nicslab approval and warranty.

Caution

This symbol indicates hazard of any operating procedure, practice, or the like that, if not correctly performed or adhered to, could result in damage to the product or loss of important data.

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Series XDAC-40CCvCV-DIFF-R4G8

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1. Introduction

Nicslab XDAC-40CCvCV-DIFF-R4G8 system is a versatile multichannel source measurement system with separated ground pin. The XDAC-40CCvCV-DIFF-R4G8 supports multiple voltage/current sourcing and voltage/current measurement. The system is suitable for sourcing and measuring low power applications from simple electronic circuits to complex photonic integrated circuits.

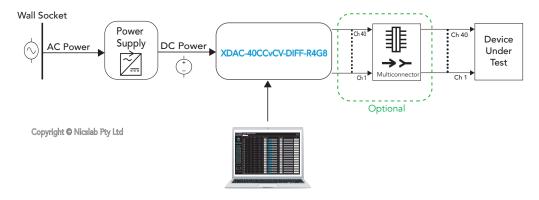
The XDAC-40CCVCV-DIFF-R4G8 provides independent 40 channels controlled by GUI and SCPI through Ethernet/USB port. The system has two modes: Constant Current (CC) ranging from ± 120 mA per channel and Constant Voltage (CV) ranging from bipolar ± 5 Volt per channel differential/no shared ground.

The features for XDAC-40CCvCV-DIFF-R4G8 in details are:

- 16-bits voltage control.
- 16-bits current control.
- Enable voltage range configuration through software (technology that enables the user to select the output range with software without lose control of the high-resolution feature).
- Flexible output configuration with 16-bit resolution: ±2.5V, ±5V, ±10V, ±18V (Premium Upgrade)
- Intuitive GUI.
- Maximum power output per channel 10 Watt.
- Save function to create database.
- Upload function to generate the registrable voltage and current pattern.
- Sequence function for continuous voltage and current.
- Short circuits protection.
- SCPI command support (Python, C# and LabVIEW).
- SCPI Library (Premium Upgrade).
- Windows, Mac, and Linux support.
- Ethernet port.

The XDAC-40CCvCV-DIFF-R4G8 is connected with DC Power then you can plug into the Device-Under-Test (DUT) or multi-connector first. The voltage/current can be controlled through GUI or SCPI command via Ethernet/Ethernet to USB port converter.

The system diagram is as follow:



Control System via Ethernet

Figure 1. XDAC-40CCvCV-DIFF-R4G8 System Diagram

The package should include the following items:

No	Item	Qty (pc)	Checklist
1	XDAC-40CCVCV-DIFF-R4G8 Box	1	
2	DC cable (Red, Green, Black)	3	
3	Multi-connector 1 (M1)	1	
4	Ribbon rainbow cable	2	
5	Ethernet cable	1	
6	USB 3.0 Ethernet Network Adaptor	1	
7	USB flash disk	1	
8	Inside USB flash disk: a. GUI Installer b. Specification & Manual c. Test Report d. Serial key (Upgrade) e. XDAC key f. Software Library (Premium) g. Template Excel (upload, demo sequence)	1	

Table 1. Checklist Items

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2. Hardware

Specification Conditions

The operating and measurement conditions are under the following conditions:

Items	Conditions		
Room Temperature	0 ~ + 40°C		
Humidity	5 ~ 80% (No Condensing)		
Power Supply Input	DC Supply Max 36V (potential at red & black DC in). Required headroom 1.4 – 2 V. For example, if you need 12 Volt output per channel then the DC input is minimum 14 V.		
Waterproof/Dustproof	To be operated under room condition		
Calibration period	2 years		

Table 2. Specification Conditions

Hardware Requirement

The requirements for the PC/Laptop to be used for this product installation are:

• Resolution Min. 1024 x 768 pixel

• Hard disk Min. 500 MB of available free space (32-bit and 64-bit operating system)

• USB Port USB 2.0

• RAM Min. 2 GB

• CPU 2.4 GHz or faster

• Ethernet port or internet connection via router

Box Descriptions

The box size is 232 (W) \times 102 (L) \times 333 (H) mm, as the pictures below:

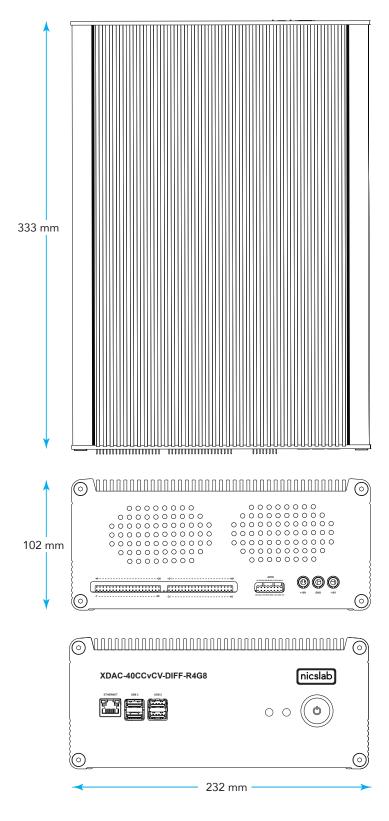


Figure 2. Product Dimension

The details of front and back panel of the box are described below:

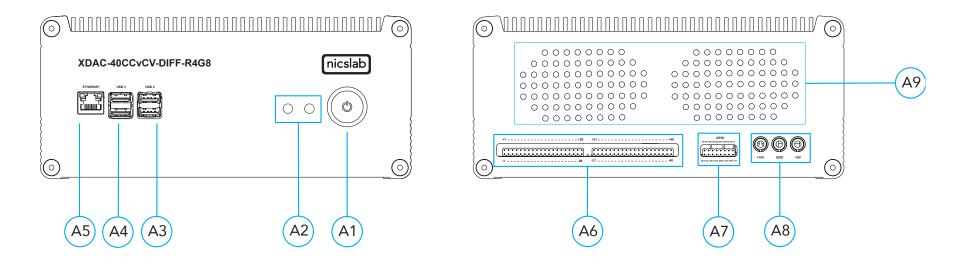


Figure 3. Front and Back Panel

Note:

A1	Power Switch	Turns the instrument on or off.	
A2	Indicator Light	Green -> GUI connected.	
		Blue -> Program ready.	
A3	USB 2.0	USB port version 2.0.	
A4	USB 3.0	USB port version 3.0.	
A5	Ethernet port	Use ethernet cable to connect or ethernet to USB port converter also possible to use if the computer doesn't have the ethernet port.	
A6	Pin Output (40 channels)	To connect to Device Under Test (DUT) using cable or multi-connector.	
A7	GPIO	You may use for external control and monitoring direct to microprocessor.	
A8	Input DC Max 42V	Caution	
		Please follow the safety notice on your DC power supply. USE ONLY ONE DC POWER SUPPLY and the input is no more than 38V.	
		Green cable inserts to GND	
		Black cable inserts to -18 V	
		Red cable inserts to +18V	
Α9	Airflow	For air circulation inside the box.	

XDAC-40CCVCV-DIFF-R4G8 Specifications

The performance specifications of Digital Analog Converter (DAC) <u>voltage</u> are listed in the table 3 below:

No	Parameter	Min	Тур	Max	Unit	Test conditions/comments
1	Resolution	16			Bits	
2	Integral nonlinearity (INL)	-1	± 0.5	1	LSB	All ranges, except ±2.5V
3	Differential Nonlinearity (DNL)	-1	± 0.5	1	LSB	Specified 16-bit monotonic
4	Total unadjusted error	-0.1	± 0.01	0.1	%FSR	All ranges except ±2.5V
5	Unipolar offset error	-0.03	± 0.015	0.03	%FSR	All unipolar ranges
6	Unipolar zero-code error	0	0.04	0.1	%FSR	All unipolar ranges
7	Bipolar zero-code error	0	0.04	0.1	%FSR	All bipolar ranges
8	Full-scale error	-0.2	± 0.075	± 0.2	%FSR	All ranges
9	Gain error	-0.1	± 0.02	0.1	%FSR	All ranges except ±2.5V
10	Unipolar offset error drift		±2		ppm of FSR/°C	All unipolar ranges
11	Bipolar offset error drift		±2		ppm of FSR/°C	All bipolar ranges
12	Gain error drift		±2		ppm of FSR/°C	All ranges
13	Output voltage drift over time		5		Ppm of FSR	$T_A = 40$ °C, Full-scale code, 1900 hours
DYN	AMIC PERFORMANCE					
14	Output Voltage Settling Time		12		μs	1% to $3%$ and $3%$ to $1%$ scale setting time to $1%$ LSB, $1%$ to $1%$ range, $1%$ RL = $1%$ Sk $1%$ c.
15	Slew Rate		4		V/µs	All range except 0 to 5V
16	Power-on glitch magnitude		0.3		V	Power-down to active DAC output, $\pm 20V$ range, Midscale code, $R_L = 5k\Omega$, $C_L = 200pF$
17	Output noise		15		µV р-р	0.1Hz to 10Hz, Midscale code, 0 to 5V range
18	Output noise density		78		nV/\Hz	1 kHz, Midscale code, 0 to 5V range
19	AC PSRR		1		LSB/V	Midscale code, frequency = 60 Hz, amplitude 200 mVpp superimposed on V_{DD} , V_{CC} or V_{SS}
20	DC PSRR		1		LSB/V	Midscale code, $V_{DD} = 5V$, $V_{CC} = 20V$ ±5%, $V_{SS} = 20V$
21	Code change glitch impulse		4		nV-s	1 LSB change around major carrier, 0 to 5V range
22	Channel to Channel AC crosstalk		4		nV-s	0 to 5V range. Measured channel at midscale. Full-scale swing on all other channels.
23	Channel to Channel DC crosstalk		0.25		LSB	0 to 5V range. Measured channel at midscale. All other channels at full-scale.
23	Digital feedthrough		1		nV-s	0 to 5V range, Midscale code, F _{SCLK} = 1MHz

The performance specifications of current buffer circuit are listed in the table 4 below:

No	Parameter	Min	Тур	Max	Unit	Test conditions/comments
POW	ER OP AMP CHARACTERISTICS					
			200	600	μV	
1	Input offset voltage			1000	μV	0°C < TA < 70°C
				1300	μV	-40°C < TA < 85°C
2	Input offset voltage drift	-10	-4	10	μV/°C	
3	Input offset current	-100		100	nA	$V_{CM} = 0 V$
4	Input bias current	-600	-160		nA	$V_{CM} = 0 V$
5	Input noise voltage		3		μV _{P-P}	
6	Input noise voltage density		15		µV/\Hz	
7	Input noise current density		3		pA/\Hz	
8	Input resistance		500			Common mode
0	input resistance		100			Differential mode
9	Input capacitance		6		pF	Pin 8 and Pin 9 to Ground
10	Input voltage range	-14.5		13.6	V	Typical
10	input voitage range	-12.0		12.0	V	Guaranteed by CMRR test
11	Common mode rejection ratio	92	105		dB	$-12V < V_{CM} < 12V$
	Power supply rejection ratio	90	100		dB	$V_{EE} = V_{-} = -5V$, $V_{CC} = V_{+} = 3V$ to 30 V
12		110	130		dB	$V_{EE} = V_{-} = -5V, V_{CC} = 30V, V_{+} = 2.5 V \text{ to } 30 V$
12		90	100		dB	$V_{EE} = V_{-} = -3V, V_{CC} = V_{+} = 5$
		110	130		dB	$V_{EE} = -30 \text{ V-} = -2.5 \text{V to } -30 \text{V},$ $V_{CC} = \text{V+} = 5 \text{V}$
13	Large-signal voltage gain	75			V/mV	$R_L = 1K$, $-12.5V < V_{OUT} < 12.5$
		40			V/mV	$R_L = 100\Omega$, $-12.5V < V_{OUT} < 12.5V$
		5			V/mV	$R_L = 10\Omega$, -5V < V_{OUT} < 5V, V- = -V- = 8V
14	Output sat voltage low		1.9	2.5	V	$V_{0L} = V_{OUT} - V_{-}$ $R_{L} = 100, V_{CC} = V_{+} = 15V, V_{EE}$ $= V_{-} = -15V$
15	Output sat voltage high		1.7	2.3	V	$V_{OH} = V + - V_{OUT}$ $R_L = 100, V_{CC} = V + = 15V, V_{EB}$ = V - = -15V
16		500	800	1200	mA	Output Low, $R_{SENSE} = 0\Omega$
	Output short-circuits current	-1000	-800	-500	mA	Output High, $R_{SENSE} = 0\Omega$
17	Slew rate	0.7	1.6		V/µs	
18	Full power bandwidth	11			kHz	V _{OUT} = 10V _{PEAK} (Note 5)
19	Gain bandwidth product		3.6		MHz	f = 10 kHz
20	Settling time		8		μV	0.01% , $V_{OUT} = 0V$ to 10V, AV = -1, $R_L = 1K$

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CURF	RENT SENSE CHARACTERISTICS					
21	Minimum current sense voltage	0.1		10	mV	$VC_{SRC} = VC_{SNK} = 0V$
22	Current sense voltage 4% of full scale	15	20	25	mV	$VC_{SRC} = VC_{SNK} = 0.5V$
23	Current sense voltage 10% full scale	45	50	55	mV	$VC_{SRC} = VC_{SNK} = 0.5V$
24	Current sense voltage 100% of full scale	480	500	520	mV	$VC_{SRC} = VC_{SNK} = 5V$
25	Current limit control input bias current	-1	-0.2	0.1	μΑ	VC _{SRC} , VC _{SNK} Pins
26	SENSE- input current	-500		500	nA	$0V < (VC_{SRC}, VC_{SNK}) < 5V$
27	FILTER input current	-500		500	nA	0V < (VC _{SRC} , VC _{SNK}) < 5V
		-500		500	nA	$VC_{SRC} = VC_{SNK} = 0V$
20	CENCE Linguit comment	200	250	300	nA	$VC_{SRC} = 5V$, $VC_{SNK} = 5V$
28	SENSE+ input current	-300	-250	-200	nA	$VC_{SRC} = 0V$, $VC_{SNK} = 5V$
		-25		25	nA	$VC_{SRC} = VC_{SNK} = 5V$
29	Current sense change with output voltage		±0.1		%	$VC_{SRC} = VC_{SNK} = 5V, -12.5V < V_{OUT} < 12.5V$
	Current sense change with supply voltage		±0.05		%	$VC_{SRC} = VC_{SNK} = 5V, 6V < (V_{CC}, V+) < 18V$
30			±0.01		%	2.5V < V+ < 18V, VCC = 18V
			±0.05		%	-18V < (V _{EE} , V-) < -2.5V
			±0.01		%	-18V < V- < -2.5V, V _{EE} = -18V
31	Current sense bandwidth		2		MHz	
32	Resistance FILTER to SENSE-	750	1000	1250	Ω	
LOGI	C I/O CHARACTERISTICS					'
33	Logic output leakage			1	μA	V = 15V
34	Logic low output level		0.2	0.4	V	I = 5mA
35	Logic output current limit		25		mA	
36	Enable logic threshold	0.8	1.9	2.5	V	
37	Enable pin bias current	-1		1	μA	
38	Total supply current		7	13	mA	V _{CC} , V+ and V-, V _{EE} connected
39	V _{CC} supply current		3	7	mA	V_{CC} , V+ and V-, V_{EE} separate
40	Supply current disabled		0.6	1.5	mA	V _{CC} , V+ and V-, V _{EE} connected, V _{ENABLE}
41	Turn-On delay		10		μs	
42	Turn-Off delay		10		μs	

Table 4. Current Limit and Buffer Performance Specification

Hardware Installation

This section describes how to install XDAC-40CCVCV-DIFF-R4G8 and how to connect your Device Under Test (DUT) to the output terminals.

The steps are as follow:

- 1. Precondition step: connect to the DC power supply (max 36 V). Make certain that DC power supply is always 'ON'.
- 2. Connect a USB cable to your workstation (PC/Laptop) via Ethernet Port or USB 3.0 Ethernet Network Adaptor.
- 3. Install the software/GUI (see the <u>Software Installation</u> section) from the flash disk or Dropbox link.
- 4. Turn ON the switch.
- 5. Wait until there is Blue LED light (the system is ready to use).
- 6. You may now open the GUI.
- 7. Connect X output to your Device Under Test (DUT).

3. Software and Graphical User Interface (GUI)

Software Requirement

The GUI software is suitable with the following operating systems:

- Windows® 7 (32-bit, 64-bit).
- Windows® 10 (32-bit, 64-bit).
- Linux
- Minimum Mac OS Catalina

Software Installation

First step is to install the XDAC_setup.exe file into your computer then double click to launch the GUI. The icon is as below:



Graphical User Interface (GUI)

The GUI details are on the next page.

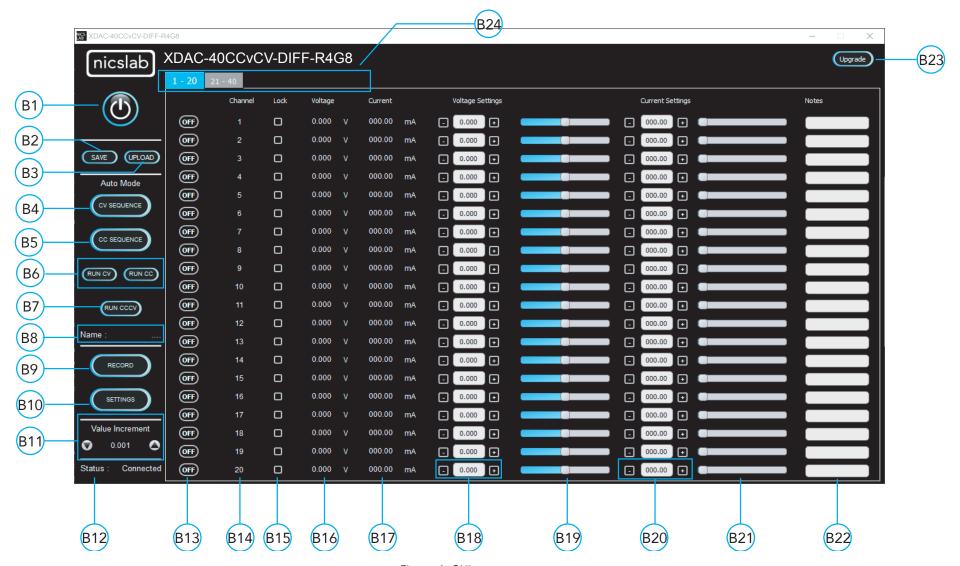


Figure 4. GUI

Note:

Callout	Description						
B1	ON/OFF Switch						
B2	Save File Button						
В3	Upload File Button						
B4	Auto Feature Sequence: Upload Table Button I CV Mode						
B5	Auto Feature Sequence: Upload Table Button I CC Mode						
B6	Auto Feature: Run Button CV and CC Mode separately						
B7	Auto Feature: Run Button CV and CC Mode combined						
B8	Name of the Sequence						
В9	Record Data Button						
B10	Setting for: Set Limit voltage and current values						
B11	Increment Settings						
B12	Status of connection						
B13	ON/OFF Button per Channel						
B14	Number of channels						
B15	Enable/Disable (Lock) Channel Controller						
B16	Voltage Value						
B17	Current Value						
B18	Voltage Value Based on Increment Setting						
B19	Voltage Settings Slider						
B20	Current Value Based on Increment Setting						
B21	Current Settings Slider						
B22	Notes						
B23	Upgrade Button						
B24	Tab Channel						

Initializing the GUI

This section shows how to initialize the GUI:

- 1. Launch the program by double clicking the "XDAC_setup_exe" icon.
- 2. Enter XDAC IP address as given. If the connection is successful, then the GUI will open and there is the Blue indicator light.



3. Press the 'ON/OFF' button (B1) to start the GUI.



4. Turn ON (B13) on each channel to input voltage and current values.



Constant Current Mode (CC Mode)

To do CC mode, you have to adjust the voltage value (B18) or move the slider (B19), then set the current value (B20 or B21). As an example, channel 1 in the below picture was given 50 Ω load.



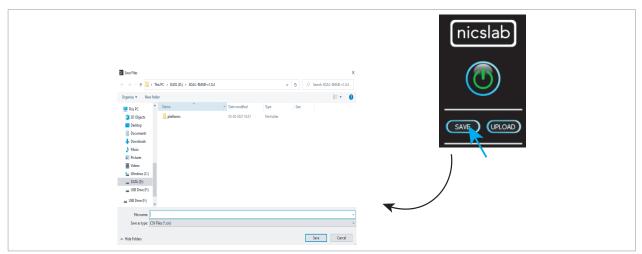
Constant Voltage Mode (CV Mode)

To do CV mode, adjust the values on value settings (B18) or move the voltage slider (B19). You may also adjust the current settings or current slider to maximum value (100 mA).

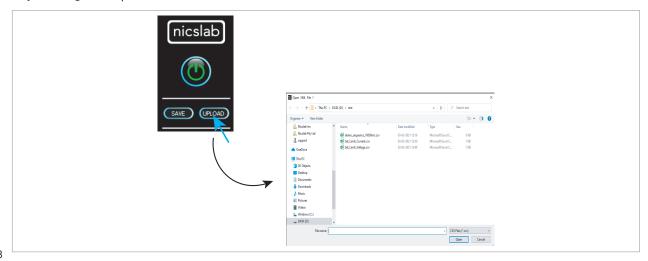


Save and Upload

You can save all the data in GUI by clicking the 'Save' button and the save file location will open.



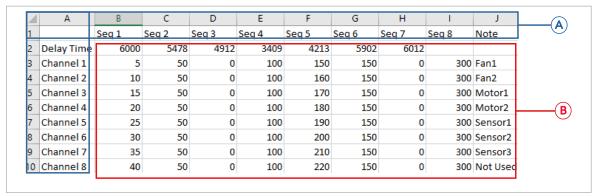
You can upload the saved .csv file or your voltage and current setting values (.csv file template provided) by clicking the 'Upload' button.



Auto Mode - Sequence

Sequence is the setting that automates the determined values of current (mA) or voltage (V) given the certain Delay Time (in millisecond).

The template of Sequence is given, then you need to input your intended values of CC Sequence (± 100 mA), CV Sequence (± 5 V) and Delay Time (in millisecond). Set the delay time more than 2 seconds to have more accurate values. To have faster response (switching time) you can set via SCPI command.



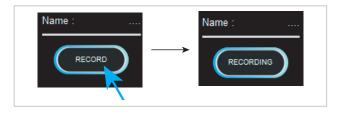
Note:

- A. Template given for CC and CV sequences.
- B. Input your intended values according to the modes (CC: 100 mA, CV: ±5V).
- 2. Upload the .csv file of sequence by pressing CC Sequence (for CC Mode) and CV Sequence (for CV Mode).
- 3. After uploading, choose sequence mode by clicking either 'Run CV' (B6 Mode for CV sequence), 'Run CC' (B6 Mode for CC sequence), or 'Run CCCV' (B7 Mode for both CC and CV sequences).

Important note: when 'Run CCCV' use the <u>same delay time</u> on the template .csv of CC and CV sequence.

Record

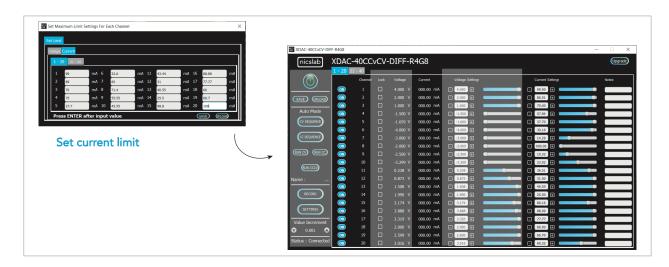
'Record' (B9) keeps data of voltage and current values. The record starts by the time you click the Record button and finish until you click again the same button. The Excel file (.csv) will be created automatically in the same folder as XDAC's GUI file.

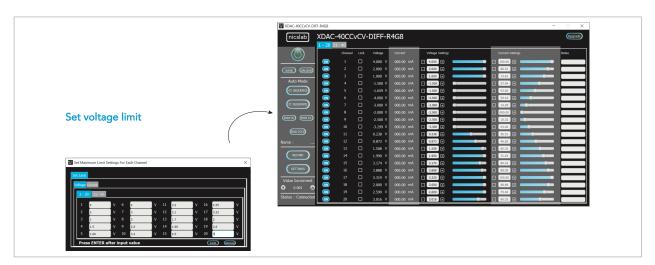


Settings

The 'Settings' feature consists of:

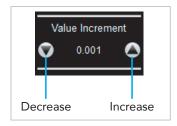
• set maximum limit for both current and/or voltage values





Value Increment Setting

In this setting, the value of the voltage and current can be incrementally changed from minimum 0.001 to 1. Adjust the arrow to increase and decrease the value increment (B11).



4. Operating XDAC through SCPI command

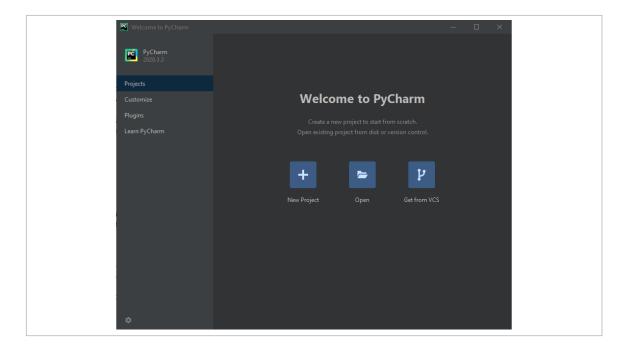
This section set guidelines to help you develop program for any language suits you best. As an example, we give the Python example.

Python Installation (Example)

Please follow steps below for dynamic programming using SCPI command through Python via TCP/IP.

The following Python and packages need to be installed:

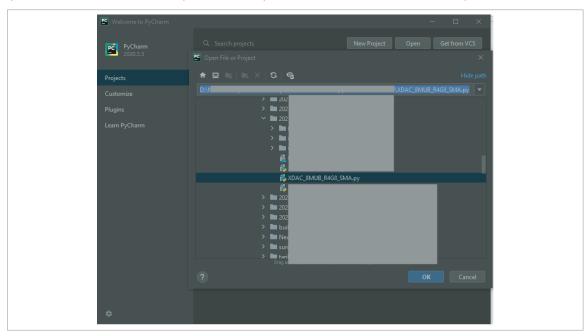
- 1. Python 2.7 or Python 3.X (download and install the latest version from www.python.org). *Tested with Python 3.9.
- 2. PyCharm 2017.3.4 or the latest version (download and install the latest version from https://www.jetbrains.com/pycharm/)



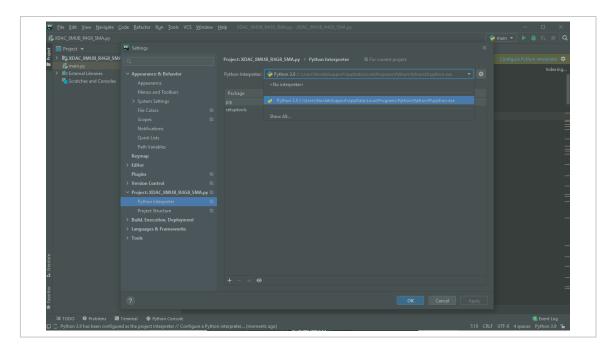
Run Python Code (Example)

To run the Python code please follow the steps below:

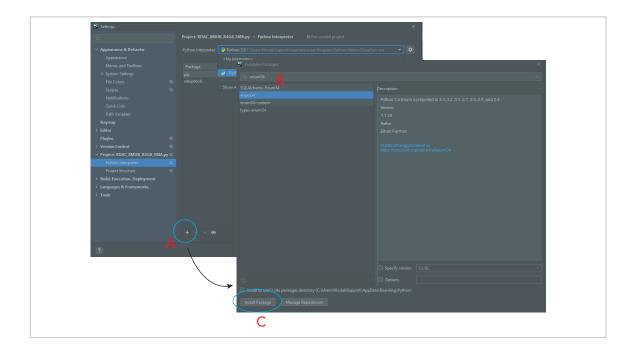
1. Open PyCharm software and open file example (e.g XDAC-8MUB-R4G8-SMA.py)



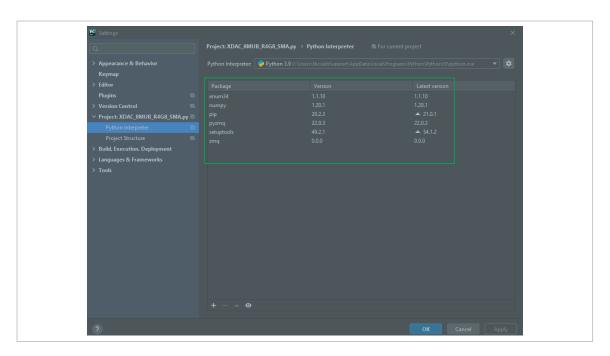
2. Configure Python interpreter (see figure below) by clicking Configure Python Interpreter link on the drop-down menu, or in File >> Settings >> Project Interpreter.



- 3. Install additional packages, for example: enum34, by:
 - A. clicking '+' button
 - B. search and choose enum34
 - C. install all the packages.



4. The packages for the Python Interpreter are listed in the green rectangle.



- 5. Select Python Configuration and choose the file name.
- 6. Run the file by clicking the green arrow button on the top right corner to test the XDAC (Please refer to the code and SCPI commands references).

Python Function (Example)

1. <u>Set XDAC measurement mode</u>

```
setXDAC(voltReadingMode, currentReadingMode)
voltReadingMode(string): "FAST" or "SLOW"
currentReadingMode(string): "FAST" or "SLOW"
example:
setXDAC("FAST", "SLOW")
```

2. <u>Set Voltage for single channel</u>

```
setChannelVoltage(channel, voltageVal)
channel (int): channel number
voltageVal (float): -5 – 5 V
```

3. Set Current for single channel

```
setChannelCurrent(channel, currentVal)
channel (int): channel number
currentVal (float): 0 - 100 mA
```

4. Set for all channels

```
setVoltageAllChannels(AllVValues)

AllVValues (float array): voltage values in array (V)
setCurrentAllChannels(AllCValues)

AllCValues (float array): current values in array (mA)
Example:

AllCValues = [100, 50, 100, 50, 100, 10, 10]

AllVValues = [-1.5, 2.5, -2.5, 4, 5, -0.75, 0.4, -3.3]
```

5. Set OFF for single channel

setOff(channel)

channel (int): channel number

6. Set averaging method and count for measurement

setReadingModeVoltage(mode, count)

setReadingModeCurrent(mode, count)

count(int): Number of measurement to be averaged

mode(string): "MOVING" or "REPEAT"

Example:

#n: read #n from sensor

Mode: "MOVING", count:5

[#1, #2, #3, #4, #5] ⇒ averaged ⇒ reading #1

[#2, #3, #4, #5, #6] ⇒ averaged ⇒ reading #2

Mode: "REPEAT", count:5

[#1, #2, #3, #4, #5] ⇒ averaged ⇒ reading #1

[#6, #7, #8, #9, #10] ⇒ averaged ⇒ reading #2

7. Read voltage or current for single channels

readSingleChannelVoltage(channel)

readSingleChannelCurrent(channel)

channel(int): channel number

return value of voltage or current in one channels

8. Read voltage or current for all channels

readAllChannelVoltage()

return list of voltage from all channels

readAllChannelCurrent()

return list of current from all channels

9. Set one channels to run automatically and record it

sweepOne(channel, seqValueV, seqValueC, duration)

channel(int): channel number

seqValueV: voltage values in array (V)

seqValueC: current values in array (mA)

Duration(int): duration in seconds

10. Shutdown

shutdown ()

SCPI Commands

The XPOW can be controlled using Standard Commands for Programmable Instruments (SCPI).

Description: Set output voltage for single channel

Format:

SETV:CHANNEL:VOLT

Example 1: Set output of channel 1 to 4 V.

SETV:1:4

Example 2: Set output of channel 3 to -0.25 V.

SETV:3:-0.25

Description: Set output current for single channel

Format:

SETC:CHANNEL:CURRENT

Example 1: Set output of channel 1 to 100 mA.

SETC:1:100

Example 2: Set output of channel 3 to 50 mA.

SETC:3:50

Description: get output voltage for single channel

Format:

MEASV:CHANNEL

Example 1: Get voltage output of channel 1.

MEASV:1

Description: get output current for single channel

Format:

MEASC:CHANNEL

Example 1: Get current output of channel 3.

MEASC:3

Description: set averaging mode and count of voltage measurement

Format:

MEASV:MODE:COUNT

Example 1: Set voltage measurement averaging to repeat mode and count 100.

MEASV:REPEAT:100

Example 2: Set voltage measurement averaging to moving mode and count 5.

MEASV:MOVING:5

Description: set averaging mode and count of current measurement

Format:

MEASC:MODE:COUNT

Example 1: Set current measurement averaging to repeat mode and count 100.

MEASC:REPEAT:100

Example 2: Set current measurement averaging to moving mode and count 5.

MEASC:MOVING:5

Description: Set zero voltage for single channel

Format:

ZERO:CHANNEL

example: Set zero of channel 1

ZERO:1

Description: Shutdown System

Format:

EXIT

5. Troubleshooting

Please use the following guidelines to identify particular problem. If the solution does not rectify the problem, contact us at support@nicslab.com.

Problem	Cause	Solution
Failed to connect at GUI	The DC power supply is OFF	Turn ON the DC power supply and switch ON the power
Failed to connect at GUI	The switch power is OFF	Switch ON the power
Failed to connect at GUI	No Green light (XDAC system is not ready)	Restart the system by pressing 'Reset' button and wait until the Green lights ON
Failed to connect at GUI	No Blue light (no data transfer)	Restart the GUI
Blue light offs when software active or software freeze	Initialization failed	Restart the software / unplug - plug USB/Ethernet connector/Press Reset Button
No channel output detected at device under test	Connection failed	Check metal pad check point to intended channel
Unable to upload the file	File format problem	Make sure the file format is .csv
No value after upload the file	File problem	Check the file content, make sure there is no blank space on each row.
Unable to use Auto Mode feature	File format problem	Check file format should be csv file. Check content format

Table 5. Troubleshooting

6. Warranty

Nicslab warrants the hardware and software designed by Nicslab to work accordingly, fulfilling the highest standard of quality product. Nicslab is not liable for consequential or incidental damages or for errors in subject to misuse, neglect, accident, modification, use in critical operation, or has been soldered or altered in any way outside stated by us or unauthorized maintenance.

Nicslab retains to change the material and technical data of this manual at any time without notice, in future editions.

Please do not hesitate to contact us at support@nicslab.com if you would like to have more information on warranty or return and refund policy.

7. Contact

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